

Übung 6 - Lösungen

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1. Wir müssen unabhängige Variationen in q und p nehmen. Also:

$$0 = \delta W_H = \int_{t_1}^{t_2} [\langle \delta p, \dot{q} \rangle + \langle p, \delta \dot{q} \rangle - H_q \delta q - H_p \delta p] dt$$
$$\stackrel{\text{P.I.}}{=} \int_{t_1}^{t_2} \langle \dot{q} - H_p, \delta p \rangle dt + \int_{t_1}^{t_2} \langle -\dot{p} - H_q, \delta q \rangle dt$$

Nach dem Lemma der Variationsrechnung:

$$\left. \begin{aligned} \dot{q} - H_p &= 0 \\ \dot{p} + H_q &= 0 \end{aligned} \right\} (*)$$

3. Schreibe (*) als

$$\frac{d}{dt} \begin{pmatrix} q \\ p \end{pmatrix} = \mathbb{J} \nabla H \quad \mathbb{J} = \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix}$$
$$\nabla = \begin{pmatrix} \frac{\partial}{\partial q} \\ \frac{\partial}{\partial p} \end{pmatrix}$$

Kettenregel

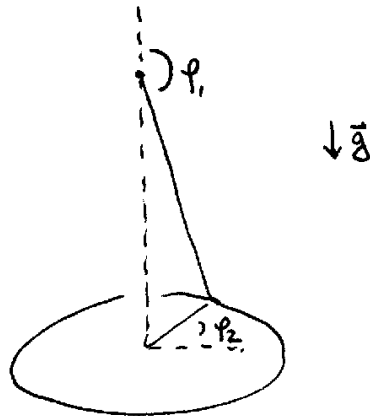
$$\Rightarrow \frac{d}{dt} H(q, p) \stackrel{\leftarrow}{=} \langle \nabla H(q, p), \begin{pmatrix} \dot{q} \\ \dot{p} \end{pmatrix} \rangle$$

$$= \langle \nabla H(q, p), \mathbb{J} \nabla H(q, p) \rangle$$

$$= 0, \text{ da } \mathbb{J} \text{ antisymmetrisch.}$$

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2.



$$E_{\text{pot}} = + mgl \cos \varphi_1$$

$$E_{\text{kin}} = \frac{1}{2} m (l \dot{\varphi}_1)^2 + \frac{1}{2} m (l \sin \varphi_1 \dot{\varphi}_2)^2$$

$$= \frac{1}{2} m l^2 (\dot{\varphi}_1^2 + \dot{\varphi}_2^2 \sin^2 \varphi_1)$$

$$L = E_{\text{kin}} - E_{\text{pot}}$$

$$\frac{\partial L}{\partial \varphi_1} = m l^2 \dot{\varphi}_1$$

$$\frac{\partial L}{\partial \varphi_2} = m l^2 \dot{\varphi}_2 \sin^2 \varphi_1$$

$$\frac{\partial^2 L}{\partial \dot{\varphi}_1^2} = m l^2 > 0$$

$$\frac{\partial^2 L}{\partial \varphi_1 \partial \varphi_2} = 0$$

$$\frac{\partial^2 L}{\partial \dot{\varphi}_2^2} = m l^2 \sin^2 \varphi_1$$

\Rightarrow Hess $\dot{\varphi} L$ ist pos. def. falls $\varphi_1 \in]0, \pi[$.

Die Legendre-Transformation bildet ab

$$(\varphi, \dot{\varphi}) \mapsto (\varphi, \nabla_{\dot{\varphi}} L) = \left(\begin{pmatrix} \varphi_1 \\ \varphi_2 \end{pmatrix}, \begin{pmatrix} m l^2 \dot{\varphi}_1 \\ m l^2 \dot{\varphi}_2 \sin^2 \varphi_1 \end{pmatrix} \right)$$

$$\Rightarrow \Omega_H =]0, \pi[\times [0, 2\pi[\times \mathbb{R}^2 = \Omega_L$$

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$$p_1 = \frac{\partial L}{\partial \dot{\varphi}_1} = m l^2 \dot{\varphi}_1 \Rightarrow \dot{\varphi}_1 = \frac{p_1}{m l^2}$$

$$p_2 = \frac{\partial L}{\partial \dot{\varphi}_2} = m l^2 \dot{\varphi}_2 \sin^2 \varphi_1 \Rightarrow \dot{\varphi}_2 = \frac{p_2}{m l^2 \sin^2 \varphi_1}$$

$$\begin{aligned} H &= \langle \dot{\varphi}, p \rangle - L(\varphi, \dot{\varphi}) \\ &= \left(\frac{p_1^2}{m l^2} + \frac{p_2^2}{m l^2 \sin^2 \varphi_1} \right) - \frac{1}{2} m l^2 \left(\left(\frac{p_1}{m l^2} \right)^2 + \left(\frac{p_2}{m l^2 \sin^2 \varphi_1} \right)^2 \right) \\ &\quad + m g l \cos \varphi_1 \\ &= \frac{1}{2} \left(\frac{p_1^2}{m l^2} + \frac{p_2^2}{m l^2 \sin^2 \varphi_1} \right) + m g l \cos \varphi_1 \end{aligned}$$

Hamilton'sche Bewegungsgleichungen:

$$\dot{\varphi}_1 = \frac{\partial H}{\partial p_1} = \frac{p_1}{m l^2}$$

$$\dot{\varphi}_2 = \frac{\partial H}{\partial p_2} = \frac{p_2}{m l^2 \sin^2 \varphi_1}$$

$$\dot{p}_1 = - \frac{\partial H}{\partial \varphi_1} = \frac{-p_2^2}{2 m l^2} \cos \varphi_1 (-2 \sin^{-3} \varphi_1) + m g l \sin \varphi_1$$

$$= \frac{p_2^2}{m l^2} \frac{1}{\sin^2 \varphi_1 \tan \varphi_1} + m g l \sin \varphi_1$$

$$\dot{p}_2 = - \frac{\partial H}{\partial p_2} = 0$$