Algorithms and Data Structures

Final Exam

July 30, 2024

1. (a) Order the following functions by their asymptotic growth rate:

 $n, \exp n, \log n, \exp(n^2), \log(\log n), (\log n)^2$

- (b) An algorithm takes as input an n-element sequence of integers. It iterates through all of its elements, executing an $O(\log n)$ -time computation if the value of the current element is even, resp. an $O(n)$ -time computation if the value of the current element is odd. What are the best-case and worst-case running times of the algorithm?
- (c) In the following, T is an instance of a standard binary tree class. It contains n nodes. What does the following code do? What is its running time as a function of n? Give a Big-Oh upper bound and a Big-Omega lower bound.

```
1 def do_something (T, p):
2 if p is not None:
3 do_something (T, T.length()4 print (T.\text{element} (p))5 do_someting (T, T.\text{right}(p))6
7 | do_something (T, T root())
```
 $(5+5+5)$

- 2. Are the following statements true or false? Explain your answer in 1–2 sentences.
	- (a) A singly linked list can be used to implement a stack such that "push" and "pop" execute in $O(1)$ -time.
	- (b) A singly linked list can be used to implement a queue such that "enqueue" and "dequeue" execute in $O(1)$ -time.
	- (c) An AVL tree can be used to sort a list $O(n \log n)$ -time.
	- (d) A heap can be used to sort a list in $O(n \log n)$ -time.
	- (e) A skip list can be used to sort a list in $O(n \log n)$ -time.

 $(2+2+2+2+2)$

3. Give the pre-order, in-order, and post-order traversals of the following binary tree:

4. Insert the keys 6, 9, 4, 3, 5, 7 into an initially empty heap. Show the heap at each step of insertion. (5)

(5)

5. Insert the keys 6, 9, 4, 3, 5, 7 into an initially empty splay tree. Show the splay tree at each step of insertion.

(You may consult the attached splay tree "cheat sheet".) (5)

- 6. Describe an algorithm that takes an undirected, connected graph $G = (V, E)$ as input and returns True if the graph is a tree and False otherwise. (5)
- 7. Consider the following greedy strategy for finding a shortest path from vertex start to vertex goal in a given connected graph.
	- (a) Initialize path to start.
	- (b) Initialize set *visited* to $\{start\}$.
	- (c) If start=goal, return path and exit. Otherwise, continue.
	- (d) Find the edge (*start*, v) of minimum weight such that v is adjacent to *start* and v is not in *visited*.
	- (e) Add v to path.
	- (f) Add v to visited.
	- (g) Set *start* equal to v and go to step (c) .

Does this greedy strategy always find a shortest path from *start* to *goal*? Either explain intuitively why it works, or give a counterexample. (5)