

Recall: Smooth surface  $M$  parameterized by  $f \in C(\bar{U}, \mathbb{R}^3) \cap C^1(\bar{U}, \mathbb{R}^3)$

$$\text{Normal field: } n = \frac{\partial f}{\partial u} \times \frac{\partial f}{\partial v} \quad f = f(u, v) \quad (u, v) \in \bar{U}$$

$$\hat{n} = \frac{n}{\|n\|} \quad (\text{well-defined for smooth } M)$$

### Surface integrals

$$\text{area } \sigma(M) = \int_U \|n\| dS$$

surface integral:  $\phi \in C(M, \mathbb{R})$

$$\int_M \phi d\sigma = \int_U \phi \circ g \|n\| dS$$

$F \in C(M, \mathbb{R}^3)$ : flux integral

$$\int_M F \cdot \hat{n} d\sigma = \int_U F \circ g \cdot n dS$$

sign depends on choice of parametrization!

### Line integrals

$$\text{length } \Delta(g) = \int_a^b \|g'(t)\| dt$$

$$\text{line integral } \int_g f ds = \int_a^b f \circ g \|g'(t)\| dt$$

$$\int_F \cdot dr = \int_g \hat{e} ds = \int_a^b F \circ g \cdot g'(t) dt$$

Examples: 1.  $M$  upper hemisphere of radius 1, outward normal field, centered at 0

$$\phi(x, y, z) = (x^2 + y^2)z$$

use parametrization  $f(\theta, \phi) = (\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta)$

$$\theta \in [0, \frac{\pi}{2}], \phi \in [0, 2\pi]$$

Recall:  $\|n\| = \sin \theta$

$$\int_M \phi d\sigma = \int_0^{2\pi} \int_0^{\frac{\pi}{2}} \sin^2 \theta (\underbrace{\cos^2 \phi + \sin^2 \phi}_1) \cos \theta \underbrace{\sin \theta}_{\|n\|} d\theta d\phi$$

$$= 2\pi \int_0^{\frac{\pi}{2}} \sin^3 \theta \cos \theta d\theta$$

$$= 2\pi \left( \int_0^1 u^3 du \right) = \frac{\pi}{2}$$

$$v = \sin \theta \Rightarrow dv = \cos \theta d\theta$$

2. Same M,

$$\vec{F} = \frac{1}{x^2 + y^2 + z^2} (1, 1, 1)$$

Here:  $\text{FoF} = (1, 1, 1)$

$$\text{Recall: } \vec{n} = \frac{\partial f}{\partial \theta} \times \frac{\partial f}{\partial \phi} = \begin{pmatrix} \sin^2 \theta & \cos \phi \\ \sin^2 \theta & \sin \phi \\ \sin \theta & \cos \theta \end{pmatrix}$$

$$\Rightarrow \int_M \vec{F} \cdot \hat{n} d\sigma = \int_U \vec{F} \cdot \vec{n} dS = \int_0^{2\pi} \int_0^\pi (\sin^2 \theta \cos \phi + \sin^2 \theta \sin \phi + \sin \theta \cos \theta) d\theta d\phi$$

$$= 2\pi \int_0^{\frac{\pi}{2}} \sin \theta \cos \theta = 2\pi \underbrace{\int_0^1 u du}_{= \frac{1}{2}} = \pi$$

Divergence Theorem:  $D \subset \mathbb{R}^k$  domain,  $V \subset D$  domain s.t.

$\bar{V} \subset D$ , bounded, regular

$\partial V$  has non-vanishing, piece-wise cont. normal field  $\vec{n}$

$$\vec{F} \in C^1(\bar{V}, \mathbb{R}^k)$$

$$\int_{\partial \bar{V}} \vec{F} \cdot \hat{n} d\sigma = \int_V \nabla \cdot \vec{F} dx$$

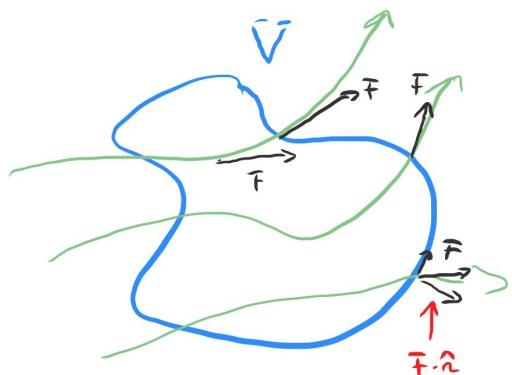
$\hat{n}$ : outward unit normal vector

## Application: Derivation of the diffusion equation

Let  $u : D \subset \mathbb{R}^3 \rightarrow \mathbb{R}$  be a concentration (mass/volume)

$$m = \int_V u \, dx, \quad \nabla \in D \text{ subdomain, arbitrary}$$

"total mass contained in  $\tilde{V}$ "



Rate of change of mass:

$$\frac{dn}{dt} = - \int_{\partial \tilde{V}} F \cdot \hat{n} \, d\sigma \quad \text{"changes in total mass are due to flux through the boundary"}$$

For diffusion: "Fick's law"  $F = -\nabla u$

$$\Rightarrow \int_V \frac{\partial u}{\partial t} \, dx = \int_{\partial \tilde{V}} \hat{n} \cdot \nabla u \, d\sigma = \int_{\tilde{V}} \underbrace{\nabla \cdot \nabla u}_{= \Delta u} \, dx \Rightarrow \boxed{\frac{\partial u}{\partial t} = \Delta u} \quad \text{"diffusion equation" or "heat equation"}$$

Stokes' theorem:  $D \subset \mathbb{R}^3$

$M \subset D$  smooth surface ( $\Rightarrow$  non-vanishing normal field), bounded, orientable

$\partial M$  has smooth parameterization, and orientation anti-clockwise w.r.t. normal field

$$F \in C^1(\bar{D}, \mathbb{R}^3)$$

$$\Rightarrow \int_{\partial M} F \cdot dx = \int_M (\nabla \times F) \cdot \hat{n} \, d\sigma$$

Compare: Green's Theorem:  $D \subset \mathbb{R}^2$

$$\int_{\partial D} F \cdot dx = \int_D \nabla^2 \cdot F \, dS$$

Green's Theorem is Stokes' theorem with  $F = \begin{pmatrix} F_1 \\ F_2 \\ 0 \end{pmatrix}$

$$\hat{n} = e_3$$

Proof. WLOG, let  $F = \begin{pmatrix} 0 \\ 0 \\ f_3 \end{pmatrix}$ .  $f(u, v)$  parameterizes  $M$

$$\int_{\partial M} F \cdot d\mathbf{x} = \int_a^b F \circ g \cdot g' dt$$

$$= \int_a^b F \circ f \circ \gamma \cdot Df \circ \gamma \cdot \gamma' dt$$

$\underbrace{\phi \circ \gamma}_{\text{grad's}}$

$$= \int_{\partial U} \phi \cdot du \stackrel{\downarrow}{=} \int_U \nabla^\perp \cdot \phi \, dS$$

$$= \int_U \nabla^\perp F_3 \circ f \cdot \begin{pmatrix} n_1 \\ n_2 \end{pmatrix} \, dS$$

$$(\nabla \times F) \circ f \cdot \mathbf{n} \, dS$$

$$= \int_M (\nabla \times F) \cdot \hat{n} \, d\sigma$$

□

$f: \bar{U} \rightarrow M$   
 $\gamma: [a, b] \rightarrow \partial \bar{U}$   
 $f \circ \gamma: [a, b] \rightarrow \partial M$   
 $\mathbf{g}' = Df \circ \gamma \cdot \gamma'$   
 $D = \left( \frac{\partial}{\partial u}, \frac{\partial}{\partial v} \right)$   
 $\text{here } F = \begin{pmatrix} 0 \\ 0 \\ f_3 \end{pmatrix}$

$$\nabla^\perp \cdot \phi = \nabla^\perp \cdot (F \circ f \cdot Df)$$

$$= \nabla^\perp \cdot (F_3 \circ f \cdot Df_3)$$

$$= \nabla^\perp (F_3 \circ f) \cdot Df_3 + F_3 \circ f \cdot \nabla^\perp \cdot Df_3$$

$$= Df_3 \circ f \cdot \nabla^\perp f \cdot Df_3$$

*(check in coordinates, or by curl grad = 0)*

$$= (\partial_1 \partial_2) F_3 \circ f \cdot \nabla^\perp \left( \frac{f_1}{f_2} \right) \cdot Df_3 \quad \boxed{\nabla^\perp f_3 \cdot Df_3 = 0}$$

$$= \nabla^\perp F_3 \circ f \cdot \underbrace{\nabla^\perp \left( -\frac{f_2}{f_1} \right) \cdot Df_3}_{\begin{pmatrix} n_1 \\ n_2 \end{pmatrix}} \quad \boxed{\text{by orthogonality}}$$