

Calculus and Elements of Linear Algebra I

Final Exam

December 14, 2020

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Some trigonometric identities:

$$\sin^2 \theta + \cos^2 \theta = 1$$

$$1 + \tan^2 \theta = \sec^2 \theta$$

$$1 + \cot^2 \theta = \csc^2 \theta$$

$$\sin^2 x = \frac{1 - \cos 2x}{2}$$

$$\sin 2x = 2 \sin x \cos x$$

$$\cos 2x = 2 \cos^2 x - 1 = 1 - 2 \sin^2 x$$

$$\tan 2x = \frac{2 \tan x}{1 - \tan^2 x}$$

$$\cos^2 x = \frac{1 + \cos 2x}{2}$$

Useful integrals:

$$\int \frac{du}{\sqrt{1-u^2}} = \arcsin u + C$$
$$\int \frac{du}{1+u^2} = \arctan u + C = -\operatorname{arccot} u + C'$$
$$\int \frac{du}{u\sqrt{u^2-1}} = \operatorname{arcsec} |u| + C$$
$$\int \sec u \, du = \ln|\sec u + \tan u| + C$$

1. Compute the limits

(a) $\lim_{t \rightarrow \infty} e^{-t} \cos(t) \sin(t)$

(b) $\lim_{\theta \rightarrow 0} \frac{1 - \cos(2\theta)}{\theta^2}$

(c) Compute the derivative of

$$f(x) = \frac{1}{x}$$

directly from its definition as the limit of a difference quotient.

(5+5+5)

$$(a) \quad |e^{-t} \cos t \sin t| = |e^{-t}| \underbrace{|\cos t|}_{\leq 1} \underbrace{|\sin t|}_{\leq 1} \leq e^{-t} \rightarrow 0 \text{ as } t \rightarrow \infty.$$

hence, by the squeeze law, $\lim_{t \rightarrow \infty} e^{-t} \cos t \sin t = 0$.

$$(b) \quad \lim_{\theta \rightarrow 0} \frac{1 - \cos 2\theta}{\theta^2} = \lim_{\theta \rightarrow 0} \frac{2 \sin^2 \theta}{\theta^2} = 2$$

where we use the standard trigonometric limit $\lim_{\theta \rightarrow 0} \frac{\sin \theta}{\theta} = 1$.

$$(c) \quad f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h} = \lim_{h \rightarrow 0} \frac{\frac{1}{x+h} - \frac{1}{x}}{h}$$
$$= \lim_{h \rightarrow 0} \frac{x - (x+h)}{h \times (x+h)} = \lim_{h \rightarrow 0} \frac{-1}{x(x+h)} = -\frac{1}{x^2}$$

2. Consider the function

$$f(x) = \frac{2-x^2}{1-x^2}.$$

What is the domain of f ? Find horizontal and vertical asymptotes, local minima, local maxima, and inflection points of f . Identify the regions where the graph of f is concave upward or concave downward. Finally, sketch the graph into the coordinate system provided. (15)

• $D(f) = \mathbb{R} \setminus \{\pm 1\}$

• $\lim_{x \rightarrow \pm\infty} f(x) = 1$, so hor. asymptote is $y=1$

• vertical asymptotes at $x = \pm 1$, note that $\lim_{|x| \rightarrow 1^-} f(x) = -\infty$,

$$\lim_{|x| \rightarrow 1^+} f(x) = +\infty.$$

• $f'(x) = \frac{-2x(1-x^2) - (-2x)(2-x^2)}{(1-x^2)^2} = \frac{2x}{(1-x^2)^2}$

critical point: $x=0$

For $x > 0$, $f'(x) > 0 \Rightarrow f$ is increasing
 $x < 0$, $f'(x) < 0 \Rightarrow f$ is decreasing } \Rightarrow loc. min at $x=0$

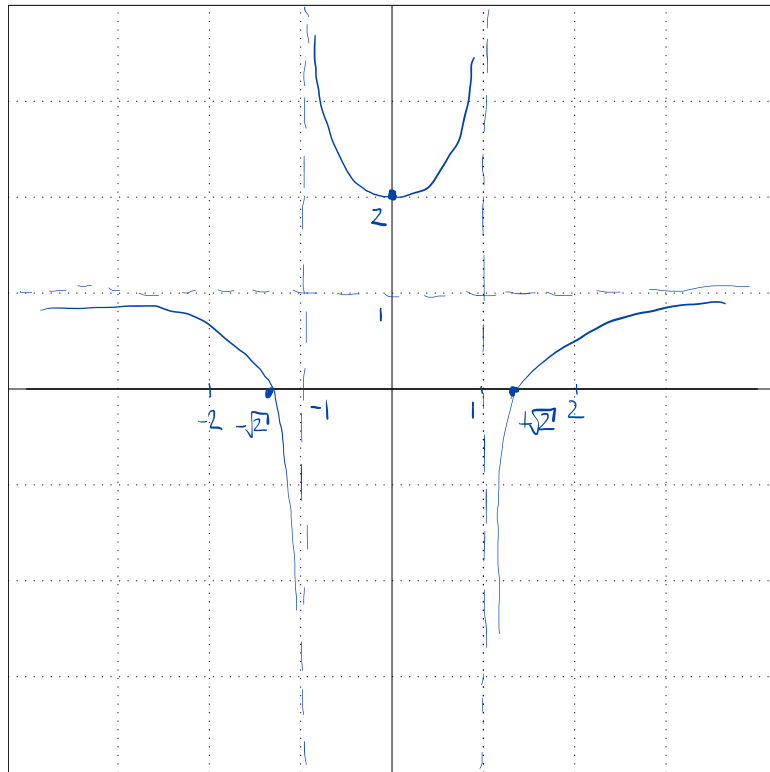
• $f''(x) = \frac{2(1-x^2)^2 - (2x)2(1-x^2)2x}{(1-x^2)^4} = 2 \frac{1-x^2+4x^2}{(1-x^2)^3}$

$$= 2 \frac{1+3x^2}{(1-x^2)^3}$$

For $|x| < 1$, $f''(x) > 0$
 $|x| > 1$, $f''(x) < 0$

³ $\Rightarrow f$ concave up
 $\Rightarrow f$ concave down

\Rightarrow no point of inflection.



3. A farmer owns a 10 km long stretch of land between two parallel rivers that are 2 km apart. What is the area of the largest rectangular corral he can enclose with

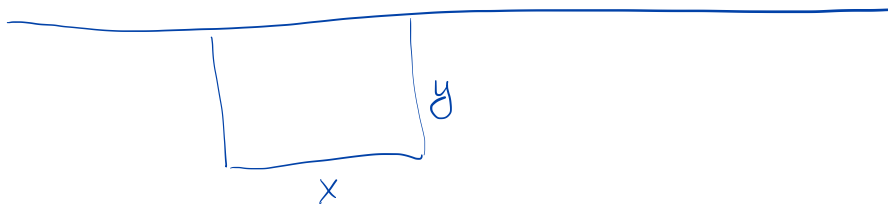
(a) 2 km of fencing,

(b) 5 km of fencing,

assuming that no fence is needed along the river?

(7+3)

(a)



$$x + 2y = L = 2 \text{ km} \quad \Rightarrow \quad y = \frac{L-x}{2}$$

$$A = xy = \frac{1}{2}x(L-x)$$

$$\Rightarrow \frac{dA}{dx} = -x + \frac{1}{2}L = 0 \quad \Rightarrow \quad x = \frac{1}{2}L \quad \Rightarrow \quad y = \frac{L - \frac{1}{2}L}{2} = \frac{1}{4}L$$

\Rightarrow The corral has a length of $x = 1 \text{ km}$ along one of the rivers and a width of $y = 0.5 \text{ km}$.

(b) With only 4 km of fencing, he can enclose the entire stretch of land he owns.

4. Use implicit differentiation to find an equation for the tangent line to the graph of $\sin(x+y) = y^2 \cos(x)$ at point $(0,0)$. (5)

$$\left(1 + \frac{dy}{dx}\right) \cos(x+y) = 2y \frac{dy}{dx} \cos x + y^2 (-\sin x)$$

At $x=0, y=0$:

$$\left(1 + \frac{dy}{dx}\right) \underbrace{\cos 0}_{=1} = 0 + 0 \quad \Rightarrow \quad \frac{dy}{dx} = -1$$

\Rightarrow The tangent line equation is $y = -x$

5. Compute the following integrals:

(a) $\int_0^1 \ln x \, dx$

(b) $\int \frac{x^2+1}{x^2-1} \, dx$

(5+10)

$$(a) \int_0^1 \ln x \, dx = \underbrace{x \ln x \Big|_0^1}_{=0} - \underbrace{\int_0^1 x \frac{1}{x} \, dx}_{=1} = -1$$

$$(b) \frac{(x^2+1) : (x^2-1)}{x^2-1} = 1 + \frac{2}{x^2-1}$$

$$\text{Partial fractions: } \frac{2}{x^2-1} = \frac{A}{x+1} + \frac{B}{x-1} = \frac{A(x-1) + B(x+1)}{x^2-1}$$

$$\Rightarrow \begin{aligned} A+B &= 0 \\ -A+B &= 2 \end{aligned}$$

$$\Rightarrow A=-1, B=1$$

$$\begin{aligned} \Rightarrow \int \frac{x^2+1}{x^2-1} \, dx &= \int \left(1 - \frac{1}{x+1} + \frac{1}{x-1} \right) \, dx = x - \ln(x+1) + \ln(x-1) + C \\ &= x + \ln \frac{x-1}{x+1} + C \end{aligned}$$

6. Is the following improper integral convergent? There is no need to compute the answer, but you should give detailed reasoning.

$$\int_0^{\infty} \frac{\ln x + e^{-x}}{1+x^2} dx$$

(10)

The integrand has a vertical asymptote at $x=0$. So let's check $x \searrow 0$ and $x \rightarrow \infty$ independently:

$$I_1 = \int_0^1 \frac{\ln x + e^{-x}}{1+x^2} dx = \int_0^1 \frac{\ln x}{1+x^2} dx + \int_0^1 \frac{e^{-x}}{1+x^2} dx$$

cont. on $[0,1]$, so no issue here

$$\text{Now } \int_0^1 \frac{\ln x}{1+x^2} dx > \int_0^1 \ln x dx = -1 \quad \text{by Q5(a).}$$

As $\frac{\ln x}{1+x^2}$ does not change sign on $[0,1]$, I_1 converges.

$$I_2 = \int_e^{\infty} \frac{\ln x + e^{-x}}{1+x^2} dx \leq 2 \int_e^{\infty} \frac{\ln x}{x^2} dx \quad \text{which converges since}$$

$$\int_e^{\infty} \frac{1}{x^d} dx \text{ converges for } d > 1.$$

As the integrand does not change sign on $[1, \infty)$, I_2 also converges.

Note: the upper bound can also be computed explicitly (not required):

$$\int_e^{\infty} \frac{\ln x}{x^2} dx = \underbrace{-\frac{1}{x} \ln x \Big|_e^{\infty}}_{= \frac{1}{e}} + \int_e^{\infty} \underbrace{x^{-3}}_{= -\frac{1}{2}x^{-2}} dx = \frac{1}{e} + \frac{1}{2}e^2$$

7. Consider the differential equation

$$\frac{dy}{dt} = t^3 y^3.$$

(a) Solve the initial value problem with $y(0) = 2$.

(b) Does this equation have equilibrium points? Are they stable or unstable?

(10+5)

$$(a) \int_2^{y(t)} \frac{dy}{y^3} = \int_0^t t^3 dt$$

$$\Rightarrow -\frac{1}{2} y^{-2} \Big|_2^{y(t)} = \frac{1}{4} t^4 \Big|_0^t$$

$$\Rightarrow \frac{1}{8} - \frac{1}{2} \frac{1}{y^2(t)} = \frac{1}{4} t^4$$

$$\Rightarrow \frac{1}{4} - \frac{1}{2} t^4 = \frac{1}{y^2(t)}$$

$$\Rightarrow y(t) = \frac{1}{\sqrt{\frac{1}{4} - \frac{1}{2} t^4}} \quad (\text{choose pos. root to match initial cond.!.})$$

(b) For $t > 0$, $\frac{dy}{dt} = 0$ iff $y = 0$,

$\frac{dy}{dt} > 0$ for $y > 0$,

$\frac{dy}{dt} < 0$ for $y < 0$

} $y = 0$ is the only equilibrium point, it is unstable.

8. Show that, for $\mathbf{u}, \mathbf{v} \in \mathbb{R}^3$,

$$\|\mathbf{u}\|^2 \|\mathbf{v}\|^2 = (\mathbf{u} \cdot \mathbf{v})^2 + \|\mathbf{u} \times \mathbf{v}\|^2.$$

(5)

$$\mathbf{u} \cdot \mathbf{v} = \|\mathbf{u}\| \|\mathbf{v}\| \cos \Theta$$

Θ : angle between \mathbf{u} and \mathbf{v}

$$\|\mathbf{u} \times \mathbf{v}\| = \|\mathbf{u}\| \|\mathbf{v}\| \sin \Theta$$

$$\Rightarrow (\mathbf{u} \cdot \mathbf{v})^2 + \|\mathbf{u} \times \mathbf{v}\|^2 = \|\mathbf{u}\|^2 \|\mathbf{v}\|^2 (\cos^2 \Theta + \sin^2 \Theta) = \|\mathbf{u}\|^2 \|\mathbf{v}\|^2$$

9. Find the general solution to the system of linear equations $Ax = b$ with

$$A = \begin{pmatrix} 2 & 0 & 2 & 4 \\ 0 & 1 & 0 & 1 \\ 2 & -1 & 2 & 3 \\ 1 & 1 & 1 & 3 \end{pmatrix}, \quad b = \begin{pmatrix} -2 \\ -2 \\ 0 \\ -3 \end{pmatrix}.$$

(10)

$$\left(\begin{array}{cccc|c} 2 & 0 & 2 & 4 & -2 \\ 0 & 1 & 0 & 1 & -2 \\ 2 & -1 & 2 & 3 & 0 \\ 1 & 1 & 1 & 3 & -3 \end{array} \right) \xrightarrow[\substack{R3-R1 \rightarrow R3 \\ R4-\frac{R1}{2} \rightarrow R4}]{\substack{R1 \rightarrow R1 \\ \frac{R1}{2}}} \left(\begin{array}{cccc|c} 1 & 0 & 1 & 2 & -1 \\ 0 & 1 & 0 & 1 & -2 \\ 0 & -1 & 0 & -1 & 2 \\ 0 & 1 & 0 & 1 & -2 \end{array} \right)$$

$$\xrightarrow[\substack{R2-R4 \rightarrow R4}]{R2+R3 \rightarrow R3} \left(\begin{array}{cccc|c} 1 & 0 & 1 & 2 & -1 \\ 0 & 1 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$$\Rightarrow x = \begin{pmatrix} -1 \\ -2 \\ 0 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix} + \mu \begin{pmatrix} 2 \\ 1 \\ 0 \\ -1 \end{pmatrix}$$

Check (not required):

$$A \begin{pmatrix} -1 \\ -2 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} -2+0 \\ 0-2 \\ -2+2 \\ -1-2 \end{pmatrix} = \begin{pmatrix} -2 \\ -2 \\ 0 \\ -3 \end{pmatrix} = b \quad \checkmark, \quad A \begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2-2 \\ 0-0 \\ 2-2 \\ 1-1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} = 0 \quad \checkmark$$

$$A \begin{pmatrix} 2 \\ 1 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 4+0-4 \\ 0+1-1 \\ 4-1-3 \\ 2+1-3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} = 0 \quad \checkmark$$

10. Let $L: \mathbb{R}^5 \rightarrow \mathbb{R}^5$ be the "shift mapping" defined as follows:

$$L \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \begin{pmatrix} 0 \\ x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix}.$$

- Show that L is a linear transformation on \mathbb{R}^5 .
- Write out the matrix S which represents L with respect to the standard basis.
- Find a basis for Range S and Ker S .
- State the "rank-nullity theorem" and verify explicitly that the result obtained in part (c) matches the statement of the theorem.

$$\begin{aligned} \text{(a)} \quad L(\lambda x + \mu y) &= L \begin{pmatrix} \lambda x_1 + \mu y_1 \\ \vdots \\ \lambda x_5 + \mu y_5 \end{pmatrix} = \begin{pmatrix} 0 \\ \lambda x_1 + \mu y_1 \\ \vdots \\ \lambda x_4 + \mu y_4 \end{pmatrix} = \lambda \begin{pmatrix} 0 \\ x_1 \\ \vdots \\ x_4 \end{pmatrix} + \mu \begin{pmatrix} 0 \\ y_1 \\ \vdots \\ y_4 \end{pmatrix} \\ &= \lambda Lx + \mu Ly \end{aligned} \quad (5+5+5+5)$$

$$\text{(b)} \quad S = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{pmatrix}$$

(c) We immediately see that columns 1-4 have pivots, so

$$\text{Range } S = \text{span} \{e_2, e_3, e_4, e_5\}$$

$$\text{Ker } S = \text{span} \{e_1\}$$

(d) Rank-nullity theorem for an $n \times m$ matrix S says that

$$\text{rank } S + \text{nullity } S = m$$

$$\text{or } \dim \text{Range } S + \dim \text{Ker } S = m.$$

$$\text{Here: } 4 + 1 = 5.$$