

1. (a) Find the normal equation for the plane that passes through the points  $(0, -1, 1)$ ,  $(2, 2, -1)$ , and  $(1, 1, 3)$ .  
 (b) Find the distance of the point  $(1, 1, 1)$  to this plane.

(5+5)

(a) Two vectors giving the orientation of the plane are

$$\vec{u} = \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} - \begin{pmatrix} 2 \\ 2 \\ -1 \end{pmatrix} = \begin{pmatrix} -2 \\ -3 \\ 2 \end{pmatrix}$$

$$\vec{v} = \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} - \begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} -1 \\ -2 \\ -2 \end{pmatrix}$$

normal vector:

$$\vec{n} = \vec{u} \times \vec{v} = \begin{pmatrix} 6 - (-4) \\ -2 - 4 \\ 4 - 3 \end{pmatrix} = \begin{pmatrix} 10 \\ -6 \\ 1 \end{pmatrix}$$

normal equation:

$$(\vec{x} - \vec{a}) \cdot \vec{n} = 0 \Rightarrow \begin{pmatrix} x_1 \\ x_2 + 1 \\ x_3 - 1 \end{pmatrix} \cdot \begin{pmatrix} 10 \\ -6 \\ 1 \end{pmatrix} = 0$$

$$\begin{aligned} \text{(b)} \quad \|\vec{n}\| &= \sqrt{100 + 36 + 1} = \sqrt{137} \\ d &= \left| \left[ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} \right] \cdot \vec{n} \right| \frac{1}{\|\vec{n}\|} = \frac{1}{\sqrt{137}} \left| \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 10 \\ -6 \\ 0 \end{pmatrix} \right| \\ &= \frac{2}{\sqrt{137}} \end{aligned}$$

2. Find the general solution to the system of linear equations  $Ax = b$  with

$$A = \begin{pmatrix} 1 & -2 & 1 & 1 \\ 2 & -4 & 2 & -2 \\ 2 & -4 & 2 & 6 \end{pmatrix}, \quad b = \begin{pmatrix} 1 \\ -2 \\ 6 \end{pmatrix}$$

Check your answer!

(10)

3. (E) Consider the matrix  $A$  from the previous question. Show that  $Ax = c$  does not have a solution when

$$c = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}.$$

(4)

- (A) Consider the matrix  $A$  from the previous question. Characterize all vectors  $c \in \mathbb{R}^3$  such that  $Ax = c$  is solvable.

(5)

$$2. \quad \left( \begin{array}{cccc|c} 1 & -2 & 1 & 1 & 1 \\ 2 & -4 & 2 & -2 & -2 \\ 2 & -4 & 2 & 6 & 6 \end{array} \right) \xrightarrow{\substack{R_3 - 2R_1 \rightarrow R_3 \\ R_2 - 2R_1 \rightarrow R_2}} \left( \begin{array}{cccc|c} 1 & -2 & 1 & 1 & 1 \\ 0 & 0 & 0 & -4 & -4 \\ 0 & 0 & 0 & 4 & 4 \end{array} \right)$$

$$\xrightarrow{\substack{-\frac{1}{4}R_2 \rightarrow R_2 \\ R_2 + R_3 \rightarrow R_3}} \left( \begin{array}{cccc|c} 1 & -2 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right) \rightarrow \left( \begin{array}{cccc|c} 1 & -2 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$$\Rightarrow x = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} + \lambda \begin{pmatrix} -2 \\ 0 \\ 0 \\ 0 \end{pmatrix} + \mu \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\text{Check: } A \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -2 \\ 6 \end{pmatrix} = c \quad \checkmark$$

$$A \begin{pmatrix} -2 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad \checkmark$$

$$A \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad \checkmark$$

$$3(E): \begin{pmatrix} 1 & -2 & 1 & 1 & 1 & 1 \\ 2 & -4 & 2 & -2 & 1 & 1 \\ 2 & -4 & 2 & 6 & -1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -2 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & -4 & -1 & -1 \\ 0 & 0 & 0 & 4 & -3 & -3 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & -2 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & -4 & -1 & -1 \\ 0 & 0 & 0 & 0 & -4 & -4 \end{pmatrix}$$

$\Rightarrow$  the system is inconsistent.

3(A): Solution (a): Find a basis for Range A; clearly

the first 3 columns are linearly dependent, so

$$v_1 = \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix} \quad \text{and} \quad v_2 = \begin{pmatrix} 1 \\ -2 \\ 6 \end{pmatrix}$$

are a basis for the Range. I.e. all vectors  $b$  of form

$$b = \lambda \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix} + \mu \begin{pmatrix} 1 \\ -2 \\ 6 \end{pmatrix} \quad (*)$$

will result in a consistent system.

Solution (b):

$$\begin{pmatrix} 1 & -2 & 1 & 1 & 1 & 1 \\ 2 & -4 & 2 & -2 & 1 & 1 \\ 2 & -4 & 2 & 6 & -1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -2 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & -4 & b_1 - 2b_2 & b_2 - 2b_1 \\ 0 & 0 & 0 & 4 & b_3 - 2b_1 & b_3 - 2b_1 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & -2 & 1 & 1 & b_1 & b_1 \\ 0 & 0 & 0 & -4 & b_2 - 2b_1 & b_2 - 2b_1 \\ 0 & 0 & 0 & 0 & b_2 + b_3 - 4b_1 & b_2 + b_3 - 4b_1 \end{pmatrix}$$

$\Rightarrow b$  must satisfy  $b_2 + b_3 - 4b_1 = 0$ .

Note: Eliminating the parameters in (\*) gives the same answer.

4. (E) Decide whether the following set of vectors is a basis of  $\mathbb{R}^3$ . Justify your answer.

$$v_1 = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}, \quad v_2 = \begin{pmatrix} 2 \\ 3 \\ -1 \end{pmatrix}, \quad v_3 = \begin{pmatrix} -1 \\ 1 \\ -2 \end{pmatrix}.$$

(A) Prove that the columns of any  $n \times k$  matrix with  $n < k$  are linearly dependent. (4)

(5)

4(E): A basis of  $\mathbb{R}^3$  consists of 3 vectors, and any linearly independent set of 3 vectors is a basis.

So we only need to check linear independence:

$$\begin{pmatrix} 1 & 2 & -1 \\ 2 & 3 & 1 \\ -1 & -1 & -2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 2 & -1 \\ 0 & -1 & 3 \\ 0 & 1 & -3 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 2 & -1 \\ 0 & -1 & 3 \\ 0 & 0 & 0 \end{pmatrix}$$

$\Rightarrow$  The vectors are l.d., hence not a basis.

(A): The column space (or range) of an  $n \times k$  matrix is a subspace of  $\mathbb{R}^n$  (or  $\mathbb{C}^n$ ), and can therefore have at most  $n$  linearly independent vectors. Since there are  $k > n$  column vectors, they must be l.d.

5. (E) Let  $A = \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{pmatrix}$ .

- (a) Find the eigenvalues and eigenvectors of A.  
 (b) Write out a diagonal matrix D and an invertible matrix S such that  $D = S^{-1}AS$ .  
 (c) Check your result by explicitly performing the matrix multiplications SD and AS.

(8+4+4)

$$\begin{aligned}
 (a) \quad p_A(\lambda) &= \det(A - \lambda I) \\
 &= \begin{vmatrix} 1-\lambda & 0 & 3 \\ 0 & 1-\lambda & 0 \\ 3 & 0 & 1-\lambda \end{vmatrix} \\
 &= (1-\lambda)^3 - (1-\lambda) \cdot 3 \cdot 3 \\
 &= (1-\lambda) [1 - 2\lambda + \lambda^2 - 9] \\
 &= (1-\lambda)(\lambda-4)(\lambda+2)
 \end{aligned}$$

(b)  $D = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & -2 \end{pmatrix}$

(c)  $S = \begin{pmatrix} 0 & -1 & 1 \\ -1 & 0 & 0 \\ 0 & -1 & -1 \end{pmatrix}$

(c)  $SD = \begin{pmatrix} 0 & -4 & -2 \\ -1 & 0 & 0 \\ 0 & -4 & 2 \end{pmatrix} = AS$

$\Rightarrow \lambda_1 = 1, \lambda_2 = 4, \lambda_3 = -2$

For  $\lambda_1$ :  $(A - \lambda_1 I)v_1 = 0$   
 $\begin{pmatrix} 0 & 0 & 3 \\ 0 & 0 & 0 \\ 3 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \Rightarrow v_1 = \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix}$

For  $\lambda_2$ :  $(A - \lambda_2 I)v_2 = 0$   
 $\begin{pmatrix} -3 & 0 & 3 \\ 3 & 0 & -3 \\ 0 & 0 & -3 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \Rightarrow v_2 = \begin{pmatrix} -1 \\ 0 \\ -1 \end{pmatrix}$

For  $\lambda_3$ :  $(A - \lambda_3 I)v_3 = 0$   
 $\begin{pmatrix} 3 & 0 & 3 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \Rightarrow v_3 = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix}$

(A) (a) Find the matrix A representing the linear transformation on  $\mathbb{R}^2$  that maps the triangle with vertices  $a = (0, 0)$ ,  $b = (1, 0)$ ,  $c = (1, 1)$  onto the triangle with vertices  $a' = (0, 0)$ ,  $b' = (\frac{1}{2}, \frac{3}{2})$ ,  $c' = (2, 2)$ .

(b) Diagonalize A. I.e., find a diagonal matrix D and a change of coordinate S such that  $D = S^{-1}AS$ .

(c) Use the result from (b) to give a concise geometric description of the linear transformation.

(5+10+5)

(a) We need:  $\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ \frac{3}{2} \end{pmatrix}$

$\Rightarrow a_{11} = \frac{1}{2}, a_{21} = \frac{3}{2}$

and  $\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 2 \end{pmatrix}$

$\Rightarrow a_{11} + a_{12} = 2, a_{21} + a_{22} = 2$

$a_{12} = 2 - \frac{1}{2} = \frac{3}{2}, a_{22} = 2 - \frac{3}{2} = \frac{1}{2}$

$\Rightarrow A = \begin{pmatrix} \frac{1}{2} & \frac{3}{2} \\ \frac{3}{2} & \frac{1}{2} \end{pmatrix}$

(b)  $\det(A - \lambda I) = (\frac{1}{2} - \lambda)^2 - \frac{9}{4} = \frac{1}{4} - \lambda + \lambda^2 - \frac{9}{4} = (\lambda + 1)(\lambda - 2)$

$\Rightarrow \lambda_1 = -1, \lambda_2 = 2$

$(A - \lambda_1 I)v_1 = 0 \Rightarrow v_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$  and  $(A - \lambda_2 I)v_2 = 0 \Rightarrow v_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$   
 $\Rightarrow D = \begin{pmatrix} -1 & 0 \\ 0 & 2 \end{pmatrix}, S = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$

(c) The transformation mirrors about the line  $x_1 = x_2$ , and stretches by a factor of 2 in the direction of the line.

6. Let  $V$  be the vector space of continuous functions on  $\mathbb{R}$  spanned by the basis

$$E = \{e^{ix}, e^{-ix}\}$$

with the usual addition and scalar multiplication.

(a) Find the matrix  $D$  which represents the derivative operator on  $V$  with respect to the basis  $E$ .

(b) Let

$$T = \{\sin x, \cos x\}.$$

Explain why  $T$  is also a basis of  $V$ , and find the matrix  $S$  for the change of basis from  $T$  to  $E$ .

(Recall that  $e^{ix} = \cos x + i \sin x$ .)

(c) Find the matrix  $C$  which represents the derivative with respect to the new basis  $T$ .

(5+5+5)

$$(a) \quad \frac{d}{dx} e^{ix} = ie^{ix} \quad \frac{d}{dx} e^{-ix} = -ie^{-ix}$$

$$\Rightarrow D = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}$$

(b) We know that

$$e^{ix} = \cos x + i \sin x \quad (*)$$

$$e^{-ix} = \cos x - i \sin x$$

$\Rightarrow$  The basis  $E$  is in the span of  $T$ , and  $T$  has the same number of vectors

$\Rightarrow T$  is also a basis of  $V$

$$\text{Clearly from } (*) \text{ we see that } S^{-1} = \begin{pmatrix} i & -i \\ 1 & 1 \end{pmatrix}$$

$$\begin{pmatrix} i & -i & | & 1 & 0 \\ 1 & 1 & | & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -1 & -i & 0 \\ 0 & 2 & i & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -1 & -i & 0 \\ 0 & 2 & i & 1 \end{pmatrix}$$

$$\Rightarrow S = \begin{pmatrix} -\frac{i}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

$$(c) \quad C = S^{-1} D S = \begin{pmatrix} i & -i \\ 1 & 1 \end{pmatrix} \begin{pmatrix} i & -i \\ 0 & -i \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

7. (E) If  $A \in M(n \times n)$ , show that  $B = A^T A$  is a symmetric matrix.

(Recall that a matrix  $C$  is symmetric if  $C = C^T$ .)

(A) Prove that the eigenvalues of any real symmetric matrix are real.

(4)

(5)

$$(E): \quad B^T = (A^T A)^T = A^T (A^T)^T = A^T A = B$$

(A): Assume

$$A v = \lambda v \quad \text{for } v \neq 0$$

and multiply from the left by  $v^H$ :

$$v^H A v = \lambda v^H v \quad (*)$$

Now take the Hermitian conjugate on both sides:

$$v^H A^H (v^H)^H = \lambda^* v^H (v^H)^H$$

$$\Rightarrow v^H A^H v = \lambda^* v^H v \quad (**)$$

So if  $A$  is Hermitian (or real symmetric), the left sides of (\*) and (\*\*) are equal, hence

$$\lambda v^H v = \lambda^* v^H v$$

$$\Rightarrow \lambda = \lambda^*$$

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so  $\lambda$  is real.